

**Amendment to the Claims**

1-6. (Cancelled)

7. (Currently Amended) A component placement recognition mark recognizing device for recognizing recognition marks for component placement that are provided corresponding to component placement positions where components are to be placed in a plurality of partition areas on a board, the component placement recognition mark recognizing device comprising:

    a recognizing camera for unit for recognizing the recognition marks linearly straightly disposed in the plurality of areas, and areas;

    a moving device for running the recognizing camera recognizing unit at a generally uniform velocity in a deposition direction in which the recognition marks are straightly disposed, linearly disposed; and

    a controller for controlling the moving device so as to run the recognizing camera at a generally uniform velocity at which images of the recognition marks can be captured, the velocity being calculated based on a time for capture of the images of the recognition marks into a storage unit and a distance between positions of the recognition marks that are adjacent to each other in the deposition direction,

    wherein the recognition marks are recognized with the use of the recognizing camera recognizing unit while the recognizing camera recognizing unit is run at the velocity by the moving device by control of the controller.

8. (Currently Amended) A component placement recognition mark recognizing device as claimed in claim 7, wherein the velocity at which the recognizing camera~~recognizing unit~~ is run by the moving device is a velocity obtained from the distance~~a distance~~ between positions of the adjoining recognition marks adjacent to each other in the deposition direction divided by the time required for capture of the images of the recognition marks~~an image of the recognition mark~~.

9. (Cancelled)

10. (Currently Amended) A component placement recognition mark recognizing method for recognizing recognition marks for component placement that are provided corresponding to component placement positions where components are to be placed in a plurality of partition areas on a board, the component placement recognition mark recognizing method comprising:

the component placement recognition mark recognizing method comprising: respectively recognizing, with a recognizing camera, the recognition marks linearly~~straightly~~ disposed in the plurality of areas, while running, by a moving device, the recognizing camera in a deposition direction in which the recognition marks are linearly disposed, at a generally uniform velocity at which images of the recognition marks can be captured and stored in a storage unit, wherein the velocity is calculated based on the time necessary for capture of the images and a distance between positions of the recognition marks that are adjacent to each other in the deposition direction~~with use of a recognizing unit while the recognizing unit is run at a generally uniform velocity in a deposition~~

~~direction in which the recognition marks are straightly disposed.~~

11-14. (Cancelled)

15. (New) A component placement recognition mark recognizing device for recognizing recognition marks for component placement that are provided corresponding to component placement positions where components are to be placed in a plurality of partition areas on a board, the component placement recognition mark recognizing device comprising:

    a recognizing camera for recognizing the recognition marks linearly disposed in the plurality of areas;

    moving means for moving the recognizing camera in a deposition direction in which the recognition marks are linearly disposed;

    a storage unit for storing recognition results obtained by the recognizing camera; and

    control means for controlling the moving device so as to continuously move the recognizing camera at a generally uniform velocity at which images of the recognition marks can be captured, wherein the velocity is calculated based on a time for capture of the images of the recognition marks into a storage unit and a distance between positions of the recognition marks that are adjacent to each other in the deposition direction,

    wherein the recognition marks are recognized with the use of the recognizing camera while the recognizing camera is run at the velocity by the moving device by control of the controller, and the recognition results are stored in the storage unit.